

MCTX3420 Team 4: Progress Report #9

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Work Done:

1. GUI Design
 - a. Start redesigning GUI to use multiple pages, less cluttered
 - b. Wrote test GUI to provide direct control over pins on the BeagleBone (for testing only).
 - c. Started work on documentation
2. Collaboration with Electronics Team
 - a. Replaced linux kernel on Electronics' BeagleBone so that they can test PWM
 - b. Began work on wiki page describing Server API and shared with Electronics team:
<https://github.com/szmoore/MCTX3420/wiki/Server-API>
 - c. Wrote Server API for direct control over pins, to be used with a test GUI (see 1e - for testing only).
 - d. Provided a pinout diagram indicating the pins that we can safely control. Some of the locations of PWM pins specified by Electronics (based on existing pinout diagrams) are incorrect. The correct locations were found by trial and error.
3. Collaboration with Sensors Team
 - a. C170 webcam arrived. Having issues getting it to work.
 - i. Although it is supported by the debian *uvc* driver, it works on a conventional laptop running debian, but not the BeagleBone. Error is "permission denied" to `/dev/video0`. Running as root doesn't fix this.
 - b. Some unspecified USB microscope is being used for the dilatometer.
4. Login and Authentication
 - a. Investigated unix style login storing encrypted passwords in a file; wrote a test program to "login"
 - i. This option would require a lot of work to add advanced features, eg: "I forgot my password"
 - b. Investigated using LDAP as a login system; wrote a test program to bind to UWA's LDAP server
 - i. LDAP provides a great deal of flexibility, and a lot of advanced features are already implemented by pheme, eg: Recording who logs in and when.
 - ii. However we need to talk to a UWA member of IT staff about using pheme.
 - c. Added Login module to server program
 - i. Only a single user is allowed to access the system. After a successful login, the server provides a SHA1 key as a cookie.
 - ii. UWA's LDAP server is currently used as the authentication mechanism.
 - d. Migrated site to SSL (HTTPS) to avoid security issues; with HTTP, username and password would be sent unencrypted.

Work Todo:

1. GUI Design
 - a. Continue to redesign GUI layout
 - b. High level system diagram; use diagram from week 3 as a starting point.
 - c. Help menus and documentation in GUI
2. Collaboration with Electronics Team
 - a. Sensor/Actuator code requires refactoring to possibly improve the sampling rate.
 - b. A test circuit should be built so that we can calibrate the ADC and get an idea of the ADC noise.
3. Collaboration with Sensors Team
 - a. Get the C170 webcam working on the BeagleBone, or we are screwed.
 - b. Write dilatometer test program
4. Login and Authentication
 - a. Determine how to use LDAP to ensure that only certain students can access the system.
 - i. Investigation shows that UWA uses LDAP to store what units you are enrolled in.
 - b. Talk to someone from UWA about binding to the UWA LDAP server. Navigate bureaucracy.

Dashboard

GPIO GPIO 5 PWM PWM 0

Error log

```

Sep 30 02:38:15 snoopx mctxserv[2598]: ERROR: ADC_Read (bbb_pin.c:477) - ADC 1 read failed: Resource tempo
Sep 30 02:46:02 snoopx mctxserv[2598]: ERROR: ADC_Read (bbb_pin.c:477) - ADC 0 read failed: Resource tempo
Sep 30 02:46:14 snoopx mctxserv[2598]: ERROR: ADC_Read (bbb_pin.c:477) - ADC 0 read failed: Resource tempo
Sep 30 02:46:22 snoopx mctxserv[2598]: ERROR: ADC_Read (bbb_pin.c:477) - ADC 1 read failed: Resource tempo
          
```

Analogue input (ADC)

AIN	0	1	2	3	4	5	6	7
Value	3888	2998	3505	1835				
Export	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>

GPIO controls

GPIO 4

Direction	Set	Result	Unexport
<input type="button" value="In"/>	<input type="button" value="Off"/>	GPIO4 reads 0	<input type="checkbox"/>

Info

This test page gives control over the BBB's pins. Select a pin that you wish to use from the relevant drop-down menu and click 'Go'.

A new widget will appear with controls relevant to that pin.

Make sure to check the error log to see if something goes wrong.

Pin out diagram

To see the pin out diagram of the BBB, click [here](#).

Export/Unexport?

To export/unexport a pin means to enable/disable it. Apart from the obvious use case, sometimes this can be required if you use two PWM channels that share the same frequency base.

You won't be able to change the frequency until you unexport one of them.

Figure 1. A pin control test page for debugging purposes

Simplified Beagle Bone Black Pin out Diagram

P9				P8			
GND	1	2	GND	DGND	1	2	DGND
DC_3.3V	3	4	DC_3.3V	EMMC2 (SD card)	3	4	EMMC2 (SD card)
VDD_5V ^[1]	5	6	VDD_5V ^[1]	EMMC2 (SD card)	5	6	EMMC2 (SD card)
SYS_5V	7	8	SYS_5V	GPIO 66	7	8	GPIO 67
PWR_BUT	9	10	SYS_RESET	GPIO 69	9	10	GPIO 68
GPIO 30	11	12	GPIO 60	GPIO 45	11	12	GPIO 44
GPIO 31	13	14	EHRPWM1A (PWM3) ^[5]	EHRPWM2B (PWM6) ^[5]	13	14	GPIO 26
GPIO 48	15	16	EHRPWM1B (PWM4) ^[5]	GPIO 47	15	16	GPIO 46
GPIO 5	17	18	GPIO 4	GPIO 27	17	18	GPIO 65
I2C	19	20	I2C	EHRPWM2A (PWM5) ^[5]	19	20	EMMC2 (SD card)
EHRPWM0B (PWM1) ^[5]	21	22	EHRPWM0A (PWM0) ^[5]	EMMC2 (SD card)	21	22	EMMC2 (SD card)
GPIO 49	23	24	GPIO 15	EMMC2 (SD card)	23	24	EMMC2 (SD card)
MCASPO	25	26	GPIO 14	EMMC2 (SD card)	25	26	GPIO 61
GPIO 115	27	28	ECAP2/MCASPO (PWM7) ^[3]	GPIO 86 ^[2]	27	28	GPIO 88 ^[2]
MCASPO	29	30	GPIO 112	GPIO 87 ^[2]	29	30	GPIO 89 ^[2]
MCASPO	31	32	VADC (1.8V)	GPIO 10 ^[2]	31	32	GPIO 11 ^[2]
AIN4 ^[4]	33	34	AGND	GPIO 9 ^[2]	33	34	GPIO 81 ^[2]
AIN6 ^[4]	35	36	AIN5 ^[4]	GPIO 8 ^[2]	35	36	GPIO 80 ^[2]
AIN2 ^[4]	37	38	AIN3 ^[4]	GPIO 78 ^[2]	37	38	GPIO 79 ^[2]
AIN0 ^[4]	39	40	AIN1 ^[4]	GPIO 76 ^[2]	39	40	GPIO 77 ^[2]
CLKOUT2 (?)	41	42	ECAP0 (PWM2) (?) ^[3]	GPIO 74 ^[2]	41	42	GPIO 75 ^[2]
GND	43	44	GND	GPIO 72 ^[2]	43	44	GPIO 73 ^[2]
GND	45	46	GND	GPIO 70 ^[2]	45	46	GPIO 71 ^[2]

[1]: VDD_5V is available only when DC jack is connected
 [2]: These GPIO pins are unavailable if HDMI is connected and the HDMI capes are enabled
 [3]: It is unknown if these pins are reserved or not (they seem to work)
 [4]: ADC pins are **1.8V MAX (DO NOT EXCEED)**
 [5]: PWM channels xA/xB *must* share the same period. To change the frequency if both are activated, the other has to be unexported.

All GPIO pins operate at **3.3V levels**. Current source/sinking capacities are limited - **4-6mA out and 8mA in (DO NOT EXCEED)**

Figure 2. BeagleBone Pinout Diagram - Don't use red or dark blue pins